

多相开关电容网络Z域不变拓扑系统分析法 ——状态变量法

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摘要 本文把开关视为固定支路,使开关电容网络变成不变拓扑网络,应用时不变网络的拓扑分析法,导出了多相开关电容网络Z域不变拓扑系统分析法——状态变量法。

关键词 开关电容网络,时不变拓扑分析,状态变量法。

1 引言

开关电容网络(SCN)的分析,国内外大多数学者是把SCN视为时变拓扑进行分相分析的。对于大规模SCN的分析,急需一种不考虑它的拓扑变化,按通常的不变拓扑一次列出电路方程的系统方法。文献[1]已给出SCN时域不变拓扑分析法,文献[2]给出了两相SCNZ域全相分析法。本文在文献[1,2]的基础上,给出了多相SCNZ域不变拓扑系统分析法——状态变量法。

2 SCN Z域不变拓扑分析法——状态变量法。

2.1 约定 (1) SCN的开关是受 N 相周期性的、均匀的、非重叠时钟脉冲控制。(2) 把开关视为固定支路,则SCN为时不变拓扑。在SCN的拓扑图中,按下列优先顺序选一棵树:(a)独立电压源支路;(b)运放输出端支路;(c)电容支路;(d)开关支路。(3) SCN的拓扑图中,支路编号次序为:(a)独立电压源支路(U);(b)运放输出端支路(P);(c)树支电容支路(CT);(d)树支开关支路(ST);(e)连支开关支路(SL);(f)连支电容支路(CL);(g)运放输入端支路(I)。(4)各支路电压和支路电荷的参考方向一致。

2.2 SCN Z域不变拓扑方程 SCN Z域不变拓扑方程是由基本割集方程、基本回路方程和支路特性方程组成。

SCN的基本割集方程为

$$DQ(Z) = 0, \quad (1)$$

其中

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申石虎 男,1932年生,教授,现从事电路理论的教学和研究工作,在网络综合、开关电容网络、网络图论和数字信号处理等方面有很多成果。

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$$D = \begin{matrix} & \text{U} & \text{P} & \text{CT} & \text{ST} & \text{SL} & \text{CL} & \text{I} \\ \text{U} & \left[\begin{array}{ccccccc} 1 & 0 & 0 & 0 & D_{Us} & D_{Uc} & D_{Ui} \end{array} \right. \\ \text{P} & \left. \begin{array}{ccccccc} 0 & 1 & 0 & 0 & D_{Ps} & D_{Pc} & D_{Pi} \end{array} \right] \\ \text{CT} & \left[\begin{array}{ccccccc} 0 & 0 & 1 & 0 & D_{Cs} & D_{Cc} & D_{Ci} \end{array} \right. \\ \text{ST} & \left. \begin{array}{ccccccc} 0 & 0 & 0 & 1 & D_{Ss} & D_{Sc} & D_{Si} \end{array} \right] \end{matrix}, \quad (2)$$

$$Q(Z) = [Q_U(Z), Q_P(Z), Q_{CT}(Z), Q_{ST}(Z), Q_{SL}(Z), Q_{CL}(Z), Q_I(Z)]^T. \quad (3)$$

$Q(Z)$ 为 SCN 各支路电荷序列 Z 变换(序列形式)组成的列向量。

SCN 的基本回路方程为

$$BV(Z) = 0, \quad (4)$$

其中

$$B = \begin{matrix} & \text{U} & \text{P} & \text{CT} & \text{ST} & \text{SL} & \text{CL} & \text{I} \\ \text{SL} & \left[\begin{array}{ccccccc} -D_{Us}^T & -D_{Ps}^T & -D_{Cs}^T & -D_{Ss}^T & 1 & 0 & 0 \end{array} \right. \\ \text{CL} & \left[\begin{array}{ccccccc} -D_{Uc}^T & -D_{Pc}^T & -D_{Cc}^T & -D_{Sc}^T & 0 & 1 & 0 \end{array} \right. \\ \text{I} & \left[\begin{array}{ccccccc} -D_{Ui}^T & -D_{Pi}^T & -D_{Ci}^T & -D_{Si}^T & 0 & 0 & 1 \end{array} \right. \end{matrix}, \quad (5)$$

$$V(Z) = [V_U(Z), V_P(Z), V_{CT}(Z), V_{ST}(Z), V_{SL}(Z), V_{CL}(Z), V_I(Z)]^T. \quad (6)$$

$V(Z)$ 是 SCN 各支路电压序列 Z 变换(序列形式)组成的列向量。

SCN 的电容支路特性为

$$Q_{CT}(Z) = C_T V_{CT}(Z) - C_T V_{CT}^{(1)}(Z), \quad (7)$$

$$Q_{CL}(Z) = C_L V_{CL}(Z) - C_L V_{CL}^{(1)}(Z). \quad (8)$$

$V_{CT}^{(1)}(Z)$ 是右移一位电容电压序列的 Z 变换(序列形式)。

由文献[2], 当把开关视为固定支路时, 引入开关变量 $S(Z)$, 则开关支路特性为

$$S_T(Z) = V_{ST}(Z) + Q_{ST}(Z), \quad (9)$$

$$S_L(Z) = V_{SL}(Z) + Q_{SL}(Z), \quad (10)$$

$$V_{ST}(Z) = \bar{\phi}_T S_T(Z), \quad (11)$$

$$Q_{ST}(Z) = \phi_T S_T(Z), \quad (12)$$

$$V_{SL}(Z) = \bar{\phi}_L S_L(Z), \quad (13)$$

$$Q_{SL}(Z) = \phi_L S_L(Z). \quad (14)$$

其中 ϕ_T 和 ϕ_L 是树支开关和连支开关控制时钟脉冲序列组成的对角阵, $\bar{\phi}_T$ 和 $\bar{\phi}_L$ 是它们的反码。

对于理想运放, 输入端口的电压和电荷恒为零, 即

$$V_I(Z) = 0, \quad (15)$$

$$Q_I(Z) = 0. \quad (16)$$

2.3 SCN Z 域全相解——全相状态方程 展开(1)式和(4)式, 把(7),(8)和(9)-(14)式代入, 消去变量 $V_I(Z)$, $Q_I(Z)$, $V_{ST}(Z)$, $Q_{ST}(Z)$, $V_{SL}(Z)$, $Q_{SL}(Z)$, $Q_{CT}(Z)$, $Q_{CL}(Z)$, 则得

$$Q_U(Z) + D_{Us}\phi_L S_L(Z) + D_{Uc}C_L V_{CL}(Z) = D_{Uc}C_L V_{CL}^{(1)}(Z), \quad (17)$$

$$Q_P(Z) + D_{Ps}\phi_L S_L(Z) + D_{Pc}C_L V_{CL}(Z) = D_{Pc}C_L V_{CL}^{(1)}(Z), \quad (18)$$

$$C_T V_{CT}(Z) + D_{Cs}\phi_L S_L(Z) + D_{Cc}C_L V_{CL}(Z) = D_{Cc}C_L V_{CL}^{(1)}(Z) + C_T V_{CT}^{(1)}(Z), \quad (19)$$

$$\phi_T S_T(Z) + D_{SS} \phi_L S_L(Z) + D_{SC} C_L V_{CL}(Z) = D_{SC} C_L V_{CL}^{[1]}(Z), \quad (20)$$

$$D_{PS}^T V_P(Z) + D_{CS}^T V_{CT}(Z) + D_{SS}^T \bar{\phi}_T S_T(Z) - \bar{\phi}_L S_L(Z) = -D_{US}^T V_U(Z), \quad (21)$$

$$D_{PC}^T V_P(Z) + D_{CC}^T V_{CT}(Z) + D_{SC}^T \bar{\phi}_T S_T(Z) - V_{CL}(Z) = -D_{UC}^T V_U(Z), \quad (22)$$

$$D_{PI}^T V_P(Z) + D_{CI}^T V_{CT}(Z) + D_{SI}^T \bar{\phi}_T S_T(Z) = -D_{UI}^T V_U(Z). \quad (23)$$

令

$$V_C(Z) = \begin{bmatrix} V_{CT}(Z) \\ V_{CL}(Z) \end{bmatrix}, \quad S(Z) = \begin{bmatrix} S_T(Z) \\ S_L(Z) \end{bmatrix}, \quad V_C^{[1]}(Z) = \begin{bmatrix} V_{CT}^{[1]}(Z) \\ V_{CL}^{[1]}(Z) \end{bmatrix}, \quad (24)$$

由(23)式,合并(19)与(22)式,(20)与(21)式,得

$$V_C(Z) = H_7 S(Z) + H_8 V_P(Z) + H_9 V_C^{[1]}(Z) + H_{10} V_U(Z), \quad (25)$$

$$V_P(Z) = -H_{16} V_C(Z) - H_{17} S(Z) - H_{19} V_U(Z), \quad (26)$$

$$H_{15} V_C(Z) + H_{20} S(Z) + H_{21} V_P(Z) = H_{22} V_C^{[1]}(Z) - H_{23} V_U(Z), \quad (27)$$

其中

$$\left. \begin{aligned} H_1 &= \begin{bmatrix} 1 & C_T^{-1} D_{CC} C_L \\ -D_{CC}^T & 1 \end{bmatrix}_{(C \times C)}, \quad H_2 = \begin{bmatrix} 0 & -C_T^{-1} D_{CS} \\ D_{SC}^T & 0 \end{bmatrix}_{(C \times S)}, \\ H_3 &= \begin{bmatrix} \bar{\phi}_T & 0 \\ 0 & \phi_L \end{bmatrix}_{(S \times S)}, \quad H_4 = \begin{bmatrix} 0 \\ D_{PC}^T \end{bmatrix}_{(C \times P)}, \quad H_5 = \begin{bmatrix} 1 & C_T^{-1} D_{CC} C_L \\ 0 & 0 \end{bmatrix}_{(C \times C)}, \\ H_6 &= \begin{bmatrix} 0 \\ D_{UC}^T \end{bmatrix}_{(C \times U)}, \quad H_7 = H_1^{-1} H_2 H_3, \quad H_8 = H_1^{-1} H_4, \quad H_9 = H_1^{-1} H_5, \\ H_{10} &= H_1^{-1} H_6, \quad H_{11} = [D_{CI}^T \ 0]_{(P \times C)}, \quad H_{12} = [D_{SI}^T \ 0]_{(P \times S)}, \quad H_{13} = H_{12} H_3, \\ H_{14} &= D_{UI}^T, \quad H_{15} = D_{PI}^T, \quad H_{16} = H_{15}^{-1} H_{11}, \quad H_{17} = H_{15}^{-1} H_{13}, \quad H_{18} = H_{15}^{-1} H_{14}, \\ H_{19} &= \begin{bmatrix} D_{CS}^T & 0 \\ 0 & D_{SC} C_L \end{bmatrix}_{(S \times C)}, \quad H_{20} = \begin{bmatrix} D_{SS}^T \bar{\phi}_T & -\bar{\phi}_L \\ \phi_T & D_{SS} \phi_L \end{bmatrix}_{(S \times S)}, \\ H_{21} &= \begin{bmatrix} D_{PS}^T \\ 0 \end{bmatrix}_{(S \times P)}, \quad H_{22} = \begin{bmatrix} 0 & 0 \\ 0 & D_{SC} C_L \end{bmatrix}_{(S \times C)}, \quad H_{23} = \begin{bmatrix} D_{US}^T \\ 0 \end{bmatrix}_{(S \times U)}. \end{aligned} \right\} \quad (28)$$

联立求解(25),(26),(27)三式,则得

$$S(Z) = H_{37} V_C^{[1]}(Z) + H_{38} V_U(Z), \quad (29)$$

$$V_P(Z) = -H_{39} V_C^{[1]}(Z) - H_{40} V_U(Z), \quad (30)$$

$$V_C(Z) = H_{41} V_C^{[1]}(Z) + H_{42} V_U(Z), \quad (31)$$

其中

$$\left. \begin{aligned} H_{24} &= 1 + H_{16} H_8, \quad H_{25} = H_{17} + H_{16} H_7, \quad H_{26} = H_{16} H_9, \\ H_{27} &= H_{18} + H_{16} H_{10}, \quad H_{28} = H_{24}^{-1} H_{25}, \quad H_{29} = H_{24}^{-1} H_{26}, \\ H_{30} &= H_{24}^{-1} H_{27}, \quad H_{31} = H_7 - H_8 H_{28}, \quad H_{32} = H_9 - H_8 H_{29}, \\ H_{33} &= H_{10} - H_8 H_{30}, \quad H_{34} = H_{20} + H_{19} H_{31} - H_{21} H_{28}, \\ H_{35} &= H_{22} + H_{21} H_{19} - H_{19} H_{32}, \quad H_{36} = H_{21} H_{30} - H_{19} H_{33} - H_{23}, \\ H_{37} &= H_{24}^{-1} H_{35}, \quad H_{38} = H_{34}^{-1} H_{36}, \quad H_{39} = H_{29} + H_{28} H_{37}, \\ H_{40} &= H_{30} + H_{28} H_{38}, \quad H_{41} = H_{32} + H_{31} H_{37}, \quad H_{42} = H_{39} + H_{31} H_{38}. \end{aligned} \right\} \quad (32)$$

(29),(30),(31)式是 SCN 的 Z 域全相解。\$V_C(Z)\$ 称作状态变量,(31)式称作全相状态方程。

2.4 SCN Z 域的分相解——分相状态方程 SCN Z 域分相解可由其全相中分出。为此须把全相解中的序列形式的 Z 变换改成通常形式的 Z 变换。对 N 相的 SCN, 有

$$\left. \begin{aligned} V_c(Z) &= \phi_1 V_c^{(1)}(Z) + \phi_2 V_c^{(2)}(Z) + \cdots + \phi_N V_c^{(N)}(Z), \\ S(Z) &= \phi_1 S^{(1)}(Z) + \phi_2 S^{(2)}(Z) + \cdots + \phi_N S^{(N)}(Z), \\ V_p(Z) &= \phi_1 V_p^{(1)}(Z) + \phi_2 V_p^{(2)}(Z) + \cdots + \phi_N V_p^{(N)}(Z), \\ V_u(Z) &= \phi_1 V_u^{(1)}(Z) + \phi_2 V_u^{(2)}(Z) + \cdots + \phi_N V_u^{(N)}(Z); \end{aligned} \right\} \quad (33)$$

$$\begin{aligned} V_c^{(i)}(Z) &= \phi_1 (V_c^{(1)}(Z))^{(i)} + \phi_2 (V_c^{(2)}(Z))^{(i)} + \cdots + \phi_N (V_c^{(N)}(Z))^{(i)} \\ &= \phi_1 Z^{-1} V_c^{(i)}(Z) + \phi_2 Z^{-1} V_c^{(i)}(Z) + \cdots + \phi_N Z^{-1} V_c^{(i)}(Z). \end{aligned} \quad (34)$$

令 $\phi_i = 1, \phi_1 = \phi_2 = \cdots = \phi_{i-1} = \phi_{i+1} = \cdots = \phi_N = 0$, 由 (29), (30), (31) 式得

$$S^{(i)}(Z) = H_{33}^{(i)} Z^{-1} V_c^{(i-1)}(Z) + H_{33}^{(i)} V_u^{(i)}(Z), \quad (35)$$

$$V_p^{(i)}(Z) = -H_{30}^{(i)} Z^{-1} V_c^{(i-1)}(Z) - H_{40}^{(i)} V_u^{(i)}(Z), \quad (36)$$

$$V_c^{(i)}(Z) = H_{41}^{(i)} Z^{-1} V_c^{(i-1)}(Z) + H_{42}^{(i)} V_u^{(i)}(Z), \quad (37)$$

$i = 1, 2, \dots, N.$

把 (35), (36), (37) 式写成矩阵形式:

$$\begin{aligned} \begin{bmatrix} S^{(1)}(Z) \\ S^{(2)}(Z) \\ \vdots \\ S^{(N)}(Z) \end{bmatrix} &= \begin{bmatrix} 0 & 0 & \cdots & 0 & Z^{-1} H_{33}^{(1)} \\ Z^{-1} H_{33}^{(2)} & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & Z^{-1} H_{33}^{(N)} & 0 \end{bmatrix} \begin{bmatrix} V_c^{(1)}(Z) \\ V_c^{(2)}(Z) \\ \vdots \\ V_c^{(N)}(Z) \end{bmatrix} \\ &+ \begin{bmatrix} H_{33}^{(1)} & & & \\ & H_{33}^{(2)} & & \\ & & \ddots & \\ & & & H_{33}^{(N)} \end{bmatrix} \begin{bmatrix} V_u^{(1)}(Z) \\ V_u^{(2)}(Z) \\ \vdots \\ V_u^{(N)}(Z) \end{bmatrix}, \end{aligned} \quad (38)$$

$$\begin{aligned} \begin{bmatrix} V_p^{(1)}(Z) \\ V_p^{(2)}(Z) \\ \vdots \\ V_p^{(N)}(Z) \end{bmatrix} &= - \begin{bmatrix} 0 & 0 & \cdots & 0 & Z^{-1} H_{30}^{(1)} \\ Z^{-1} H_{30}^{(2)} & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & Z^{-1} H_{30}^{(N)} & 0 \end{bmatrix} \begin{bmatrix} V_c^{(1)}(Z) \\ V_c^{(2)}(Z) \\ \vdots \\ V_c^{(N)}(Z) \end{bmatrix} \\ &- \begin{bmatrix} H_{40}^{(1)} & & & \\ & H_{40}^{(2)} & & \\ & & \ddots & \\ & & & H_{40}^{(N)} \end{bmatrix} \begin{bmatrix} V_u^{(1)}(Z) \\ V_u^{(2)}(Z) \\ \vdots \\ V_u^{(N)}(Z) \end{bmatrix}, \end{aligned} \quad (39)$$

$$\begin{bmatrix} 1 & 0 & \cdots & 0 & -Z^{-1}H_{41}^{(1)} \\ -Z^{-1}H_{41}^{(2)} & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & -Z^{-1}H_{41}^{(N)} & 1 \end{bmatrix} \begin{bmatrix} V_c^{(1)}(Z) \\ V_c^{(2)}(Z) \\ \vdots \\ V_c^{(N)}(Z) \end{bmatrix} - \begin{bmatrix} H_{42}^{(1)} \\ H_{42}^{(2)} \\ \vdots \\ H_{42}^{(N)} \end{bmatrix} \begin{bmatrix} V_U^{(1)}(Z) \\ V_U^{(2)}(Z) \\ \vdots \\ V_U^{(N)}(Z) \end{bmatrix} \quad (40)$$

(38),(39),(40)式是 SCN Z 域分相解;(40)式是 SCN 的分相状态方程。从分相状态方程(40)式解出状态向量 $[V_c^{(1)}(Z), V_c^{(2)}(Z), \dots, V_c^{(N)}(Z)]^T$, 代入(38)或(39)式, 便可解出向量 $[S^{(1)}(Z), S^{(2)}(Z), \dots, S^{(N)}(Z)]^T$ 或 $[V_P^{(1)}(Z), V_P^{(2)}(Z), \dots, V_P^{(N)}(Z)]^T$ 。

3 示例

图 1 为一三相有源 SCN, 求其电压传递函数。

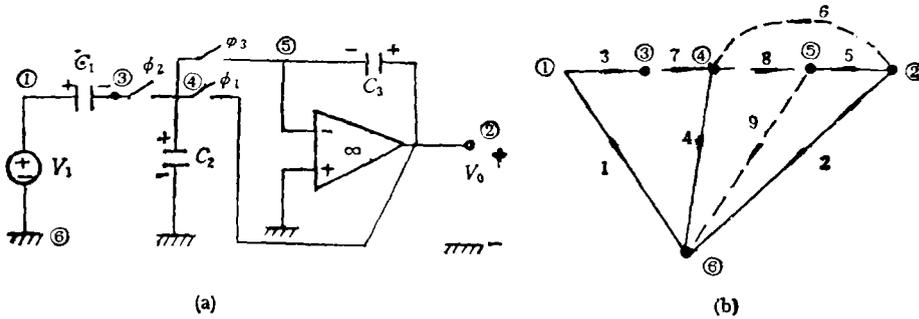


图 1 三相有源 SCN 及其拓扑图

解

	U	P	CT	SL	I
U	1	0	0	0	0
P	0	1	0	0	0
CT	0	0	1	0	0
SL	0	0	0	1	0
I	0	0	0	0	1

$D_{Us} = [0 \ 1 \ 0], D_{Ul} = [0], D_{Ps} = [1 \ 0 \ -1], D_{Pl} = [1],$

$D_{Cs} = \begin{bmatrix} 0 & -1 & 0 \\ -1 & -1 & 1 \\ 0 & 0 & 1 \end{bmatrix}, D_{Cl} = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}, C_T = \begin{bmatrix} C_1 \\ C_2 \\ C_3 \end{bmatrix}, \phi_L = \begin{bmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \end{bmatrix}$

通过 H_1-H_2 矩阵的填写或计算, 则得

$$H_{41} = \begin{bmatrix} \frac{C_1}{C_1 + C_2\phi_2} & -\frac{C_2\phi_2}{C_1 + C_2\phi_2} & 0 \\ -\frac{C_1\phi_2}{C_1 + C_2\phi_2} & \frac{C_2\phi_2}{C_1 + C_2\phi_2} & \frac{C_1\phi_1}{C_1 + C_2\phi_2} \\ 0 & -\frac{C_1C_2\phi_3}{C_3(C_1 + C_2\phi_2)} & 1 \end{bmatrix}, \quad H_{42} = \begin{bmatrix} \frac{C_2\phi_2}{C_1 + C_2\phi_2} \\ \frac{C_1\phi_2}{C_1 + C_2\phi_2} \\ 0 \end{bmatrix}$$

全相状态方程为

$$\begin{bmatrix} V_{c_1}(Z) \\ V_{c_2}(Z) \\ V_{c_3}(Z) \end{bmatrix} = \begin{bmatrix} \frac{C_1}{C_1 + C_2\phi_2} & -\frac{C_2\phi_2}{C_1 + C_2\phi_2} & 0 \\ -\frac{C_1\phi_2}{C_1 + C_2\phi_2} & \frac{C_2\phi_2}{C_1 + C_2\phi_2} & \frac{C_1\phi_1}{C_1 + C_2\phi_2} \\ 0 & -\frac{C_1C_2\phi_3}{C_3(C_1 + C_2\phi_2)} & 1 \end{bmatrix} \begin{bmatrix} V_{c_1}^{(1)}(Z) \\ V_{c_2}^{(1)}(Z) \\ V_{c_3}^{(1)}(Z) \end{bmatrix} + \begin{bmatrix} \frac{C_2\phi_2}{C_1 + C_2\phi_2} \\ \frac{C_1\phi_2}{C_1 + C_2\phi_2} \\ 0 \end{bmatrix} V_U(Z).$$

分相状态方程

$$\begin{bmatrix} 1 & 0 & -Z^{-1}H_{41}^{(1)} \\ -Z^{-1}H_{41}^{(2)} & 1 & 0 \\ 0 & -Z^{-1}H_{41}^{(3)} & 1 \end{bmatrix} \begin{bmatrix} V_c^{(1)}(Z) \\ V_c^{(2)}(Z) \\ V_c^{(3)}(Z) \end{bmatrix} = \begin{bmatrix} H_{42}^{(1)} \\ H_{42}^{(2)} \\ H_{42}^{(3)} \end{bmatrix} \begin{bmatrix} N_U^{(1)}(Z) \\ V_U^{(2)}(Z) \\ V_U^{(3)}(Z) \end{bmatrix},$$

其中

$$H_{41}^{(1)} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}, \quad H_{42}^{(1)} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \quad H_{41}^{(2)} = \begin{bmatrix} \frac{C_1}{C_1 + C_2} & -\frac{C_2}{C_1 + C_2} & 0 \\ -\frac{C_1}{C_1 + C_2} & \frac{C_1}{C_1 + C_2} & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

$$H_{42}^{(2)} = \begin{bmatrix} \frac{C_2}{C_1 + C_2} \\ \frac{C_1}{C_1 + C_2} \\ 0 \end{bmatrix}, \quad H_{41}^{(3)} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & -\frac{C_2}{C_3} & 1 \end{bmatrix}, \quad H_{42}^{(3)} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix};$$

$$V_c^{(i)}(Z) = [V_{c_1}^{(i)}(Z), V_{c_2}^{(i)}(Z), V_{c_3}^{(i)}(Z)]^T, \quad i = 1, 2, 3;$$

$$V_U^{(1)}(Z) = 0, \quad V_U^{(2)}(Z) = V_U^{(2)}(Z), \quad V_U^{(3)}(Z) = 0.$$

用高斯消去法, 从分相状态方程中解得 $V_{c_1}^{(1)}(Z)$, $V_{c_2}^{(2)}(Z)$, $V_{c_3}^{(3)}(Z)$, 求得电压传递函数为

$$H^{(12)} = V_{C_3}^{(1)}(Z)/V_I^{(2)}(Z) = \frac{C_1 C_2 Z^{-2}(Z^{-3} - 1)}{C_3(C_1 + C_2) - (2C_1 C_3 + C_2 C_3 - C_2^2)Z^{-3} + C_1 C_3 Z^{-6}},$$

$$H^{(22)} = V_{C_3}^{(2)}(Z)/V_I^{(2)}(Z) = \frac{C_1 C_2 Z^{-3}(Z^{-3} - 1)}{C_3(C_1 + C_2) - (2C_1 C_2 + C_2 C_3 - C_2^2)Z^{-3} + C_1 C_3 Z^{-6}},$$

$$H^{(32)} = V_{C_3}^{(3)}(Z)/V_I^{(2)}(Z) = \frac{C_1 C_2 Z^{-1}(Z^{-3} - 1)}{C_3(C_1 + C_2) - (2C_1 C_2 + C_2 C_3 - C_2^2) + C_1 C_3 Z^{-6}}.$$

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A SYSTEMATIC TIME-INVARIANT TOPOLOGY ANALYSIS METHOD OF MULTIPHASE SCN IN Z-DOMAIN —A STATE VARIABLE APPROACH

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Abstract In this paper, switches are considered as fixed branches, thereby the topology of a SCN becomes time-invariant. The technique for analysis of time-invariant networks is applied to SCN's. A systematic time-invariant topology analysis method of multiphase SCN's in Z-domain—a state variable approach is derived.

Key words Switched-capacitor networks, Time-invariant topology analysis, State variable approach